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**Automotive MEMS (Micro
Electromechanical System)
Sensor Research Report,
2025**

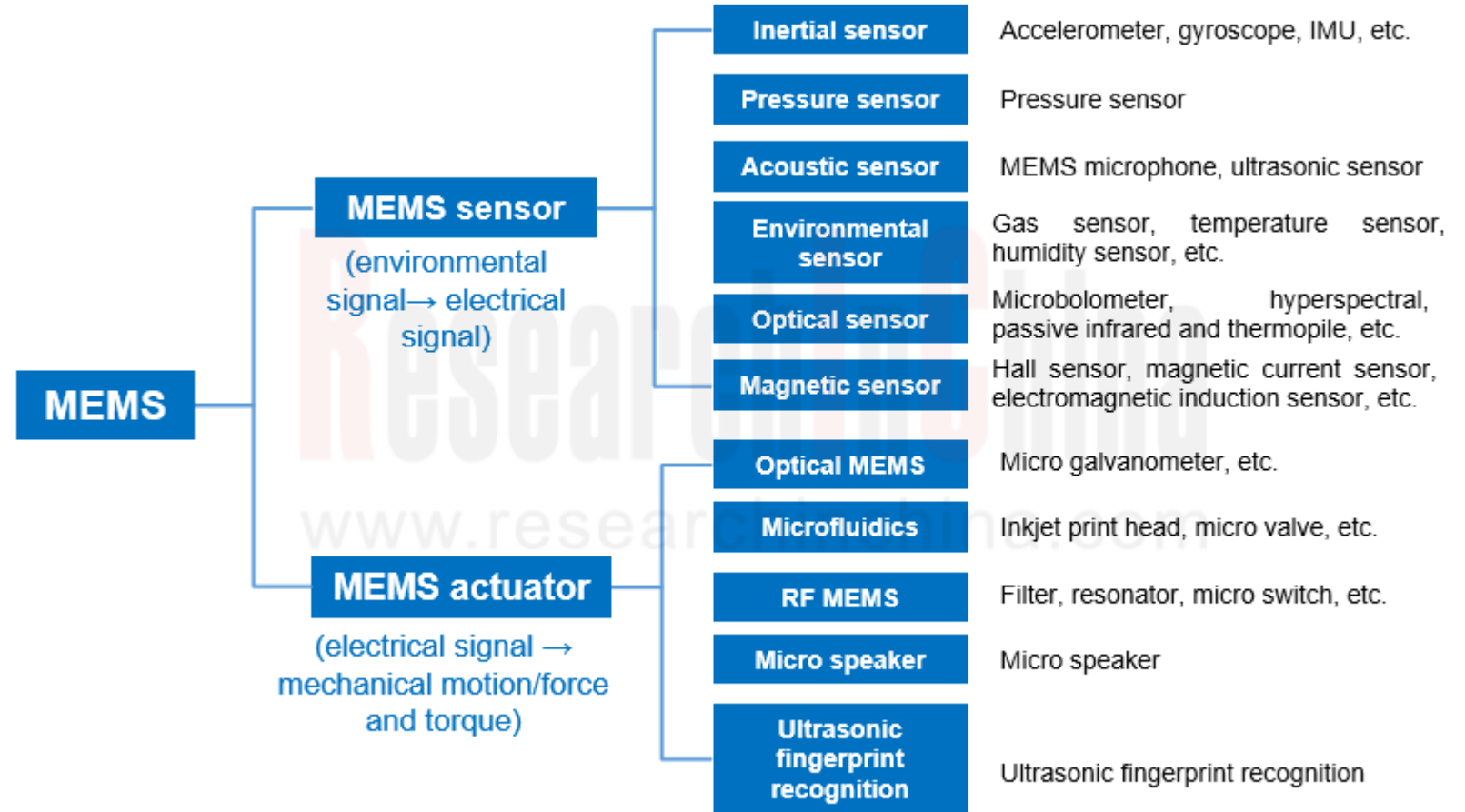
Jan. 2025

Automotive MEMS Research: A single vehicle packs 100+ MEMS sensors, and the pace of product innovation and localization are becoming much faster

MEMS (Micro Electromechanical System) is a micro device or system that integrates micromechanical structures, micro sensors, micro actuators, signal processing and control circuits, communication interfaces and power modules on a chip according to functional requirements. MEMSs are mainly divided into MEMS sensors and MEMS actuators.

MEMS sensor is composed of MEMS chip and ASIC packaging. The MEMS chip converts external physical, chemical, biological and other signals into electrical signals. The ASIC reads the electrical signals, and processes and outputs them, thereby acquiring external information. Compared with traditional sensors, the MEMS sensor can integrate all accessories on a very small MEMS chip, and features high integration, miniaturization, intelligence, low weight, low power consumption and multiple functions.

Classification of MEMS



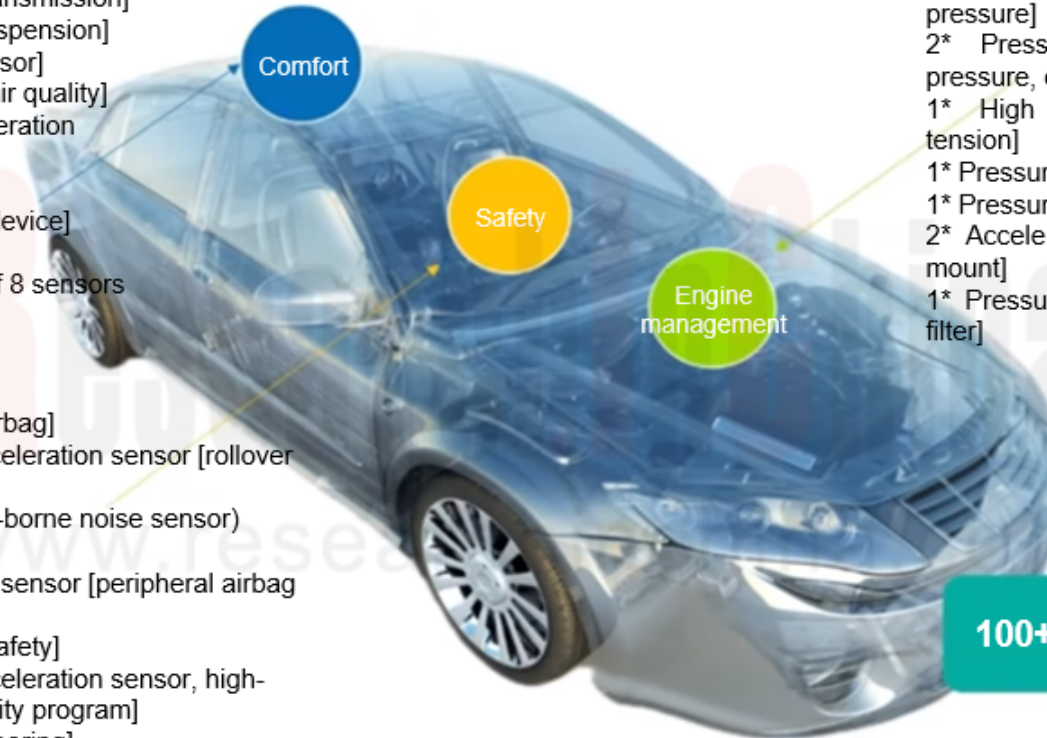
Source: ResearchInChina

Application of MEMS Sensors in Vehicles

In the automotive field, MEMS sensors are widely used in automotive ADAS, intelligent cockpits, body comfort systems, powertrains and chassis systems. They find application in high-precision positioning, healthy cockpit (air quality), in-car heartbeat monitoring, smart car key, active noise reduction, heat pump air conditioner, airbag, engine, battery management system (BMS), electronic stability program, and anti-lock braking system (ABS), electronically controlled suspension and tire pressure monitoring system (TPMS).

- 2* Pressure sensor [automatic transmission]
- 5* Acceleration sensor [active suspension]
- 1* Pressure sensor [humidity sensor]
- 2* Gas sensor [air conditioning, air quality]
- 1* Angular velocity sensor, acceleration sensor [cruise]
- 3* Microphone [phone]
- 1* Bolometer array [night vision device]
- 1* Acceleration sensor [alarm]
- 16 sensors in total, an average of 8 sensors per seat

- 2* High-g acceleration sensor [airbag]
- 1* Angular rate sensor, low-g acceleration sensor [rollover sensing]
- 1* Acceleration sensor (structure-borne noise sensor) [Airbag]
- 4* Acceleration sensor, pressure sensor [peripheral airbag sensor]
- 2* Pressure sensor [pedestrian safety]
- 1* Angular rate sensor, low-g acceleration sensor, high-pressure sensor [electronic stability program]
- 1* Variable rate sensor [active steering]
- 1* Acceleration sensor [automotive emergency call]
- 4* Pressure sensor, acceleration sensor [TPMS]
- 1* Pressure sensor [occupant detection]



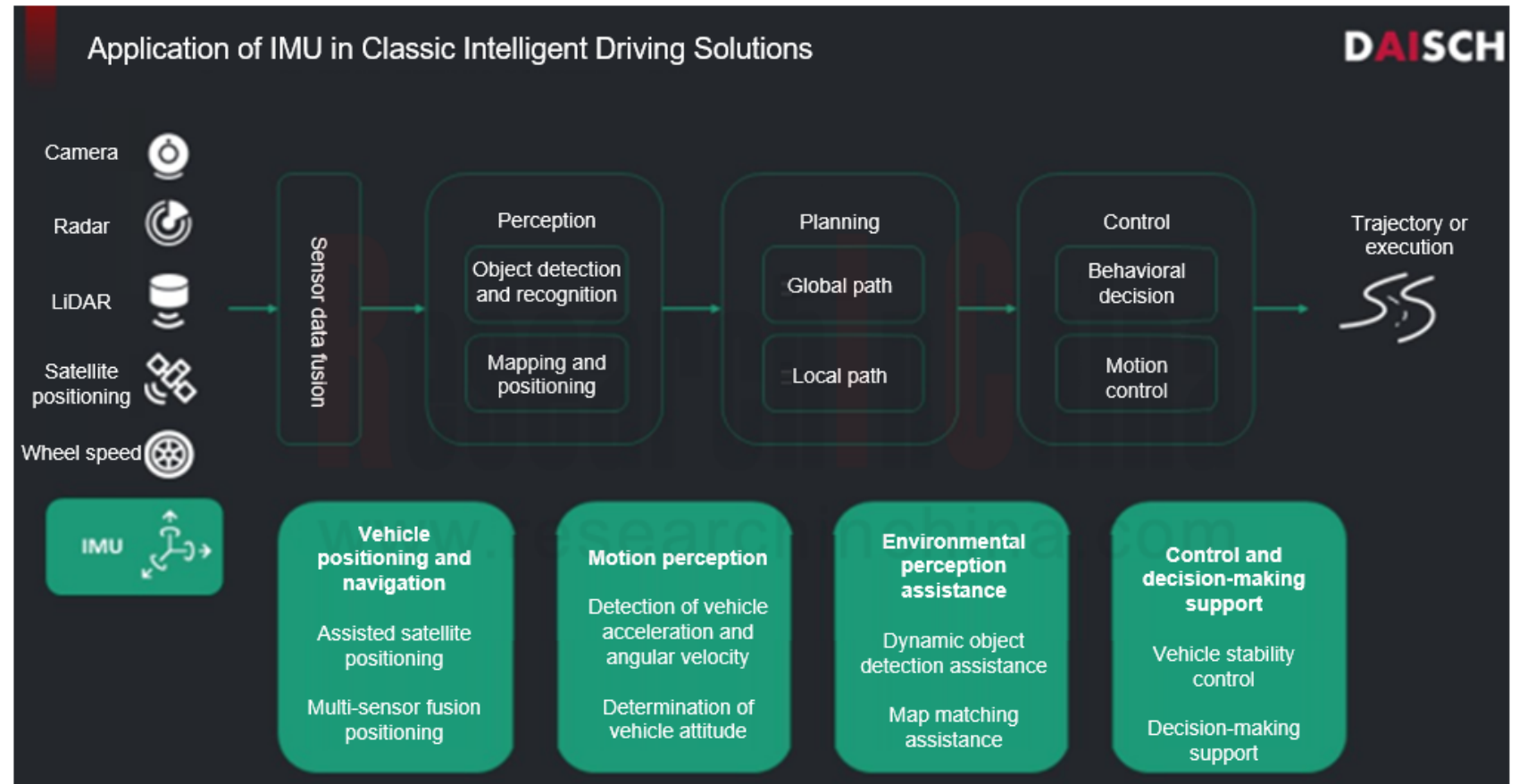
- 1* Mass flow sensor
- 1* Pressure sensor [atmospheric pressure]
- 2* Pressure sensor [manifold air pressure, oil circuit]
- 1* High pressure sensor [normal tension]
- 1* Pressure sensor [tank pressure]
- 1* Pressure sensor [start-stop function]
- 2* Acceleration sensor [active engine mount]
- 1* Pressure sensor [diesel particulate filter]

Source: MEMSIC

MEMS Inertial Sensor

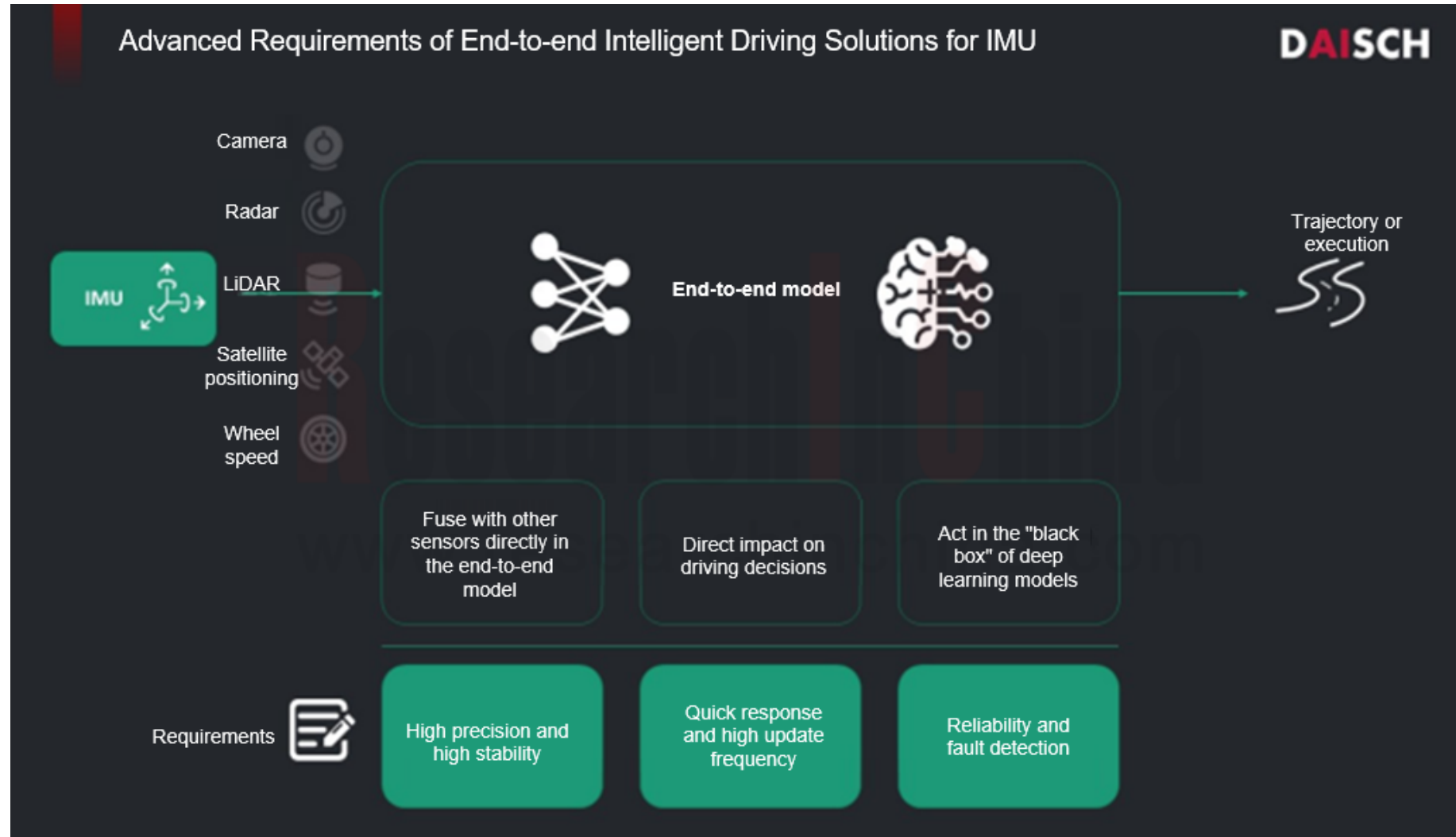
Among MEMS products for automotive applications, pressure sensors, inertial sensors and microphones employ the most MEMS sensors, sweeping 99% of automotive MEMS. In the future, with vehicle intelligence, system integration and the R&D of MEMS-related devices, more diversified MEMS sensors will be applied to vehicles.

MEMS inertial sensors are the basis for intelligent driving perception of new energy vehicles. They mainly include MEMS gyroscope, MEMS accelerometer, and MEMS IMU. They can be used to measure the acceleration and angular velocity of vehicles while driving, and provide real-time vehicle motion posture and trajectory. MEMS inertial sensors (accelerometer, gyroscope) were first used in airbags and electronic stability control systems. As autonomous driving develops, the application of MEMS IMUs in high-precision positioning and navigation scenarios has been expanded.



Source: DAISCH

MEMS IMU integrates MEMS accelerometer, MEMS gyroscope, and motion/attitude algorithm. In classic intelligent driving scenarios, MEMS IMU is often used in modules and functions such as vehicle positioning and navigation, motion perception, environmental perception assistance, control and decision-making support.



Source: DAISCH

In end-to-end intelligent driving solutions, the solution of integrating IMUs into domain controllers has become the mainstream option. With the evolution of autonomous driving, vehicles have higher accuracy and safety requirements for perception and positioning. It is necessary to ensure that vehicle position information is highly accurate and reliable. In particular, L3/L3+ autonomous vehicles need to have higher-precision positioning. The requirements for MEMS IMUs will become ever higher:

- **High accuracy and stability:** High-precision IMUs can provide more accurate vehicle attitude information to help systems better understand the position and direction of vehicles in space. Also the stability of IMUs is crucial to the reliability of systems. During long-term operation, IMUs need to maintain stable performance and output reliable data, without being affected by environmental factors such as temperature changes and vibration.
- **Quick response and high update frequency:** End-to-end intelligent driving systems need to make a quick response to environmental changes, so IMUs need to respond quickly and update data frequently.
- **Compatibility with deep learning models:** End-to-end intelligent driving systems generally use deep learning models to process sensor data, so IMUs need to provide data formats that are compatible with deep learning models.
- **High reliability and fault analysis:** End-to-end intelligent driving systems pose extremely high safety requirements, including normal operation in various harsh environments such as high temperature, low temperature, high humidity and intense vibration, so IMUs need to offer high reliability. Moreover due to the complexity of end-to-end systems, IMUs need to have the ability to detect and diagnose faults. When IMU fails, the intelligent driving system can detect the failure in time and take corresponding measures, for example, switching to backup sensors or decelerating, so as to ensure the safety of the vehicle.

In November 2024, Murata Manufacturing Co., Ltd. unveiled its latest innovation in automotive sensor technology, the SCH1633-D01. The 6-axis MEMS inertial sensor is designed to meet the increasing demand for precision in autonomous driving (AD), advanced driver-assistance systems (ADAS), and other key automotive functions, including inertial navigation, vehicle stability control, and headlight alignment. It is the smallest product among Murata's automotive-grade IMUs.

The automotive 6-axis MEMS IMU integrates a 3-axis accelerometer and a 3-axis gyroscope, with the acceleration range of $\pm 8g$, the angular velocity range of $\pm 62.5\text{dps} \sim \pm 300\text{dps}$, and built-in orthogonal error compensation. It enables extremely smooth and high-resolution output. The IMU features time synchronization, providing the signals required for GNSS dead reckoning, vehicle attitude measurement, camera/LiDAR/radar tilt detection, to handle the time misalignment between these signals.

Murata's New Automotive 6-axis MEMS IMU - SCH1633-D01



Source: Murata Manufacturing Co., Ltd.

In the field of automotive MEMS IMU, most high-precision MEMS IMUs are imported

In the field of automotive MEMS IMU, **most high-precision MEMS IMUs are imported**. As China's new energy vehicle industry gains an edge and opportunities, automotive MEMS IMUs made in China are accelerating the pace of replacing imports. Chinese companies such as QST, Asensing Technology, MT Microsystems, AAC Technologies, Huaxin Semiconductor, DAISCH and Aceinna are deploying automotive MEMS IMUs.

In July 2024, QST released new six-axis MEMS IMUs, QMI8A01 and QMI8A01z. QMI8A01z has been certified by AEC-Q100 Grade 2.

The board-level sensitivity error of the MEMS gyroscope in QMI8A01z reaches $\pm 1\%$, and the TCS of the MEMS accelerometer is $0.0025\%/^{\circ}\text{C}$. In harsh application scenarios, QMI8A01z can minimize the impact of the environment and help technicians develop more flexible algorithms. In addition, it supports SPI, I2C, and I3C communication protocols. To make it easier for application developers to develop, the sensor has a built-in intelligent algorithm which mainly integrates AnyMotion, No-Motion, and SignificantMotion to detect motion/stationary/continuous movement and output the corresponding interrupt signal.

Main Technical Features of QST's Six-axis MEMS IMUs - QMI8A01 & QMI8A01z

	QMI8A01z	QMI8A01
Acceleration range	$\pm 2g \sim \pm 16g$	
Gyroscope range	$\pm 16^{\circ} /s \sim \pm 2048^{\circ} /s$	
Gyroscope sensitivity	$\pm 1\%$	
Accelerometer TCS	$0.0025\%/^{\circ}\text{C}$	
Noise	/	Gyroscope: $13 \text{ mdps}/\sqrt{\text{Hz}}$ Accelerometer: $150\mu\text{g}/\sqrt{\text{Hz}}$
Automotive-grade certification	AEC-Q100 Grade 2	/
Communication interface	I ² C+3-wire/4-wire SPI	I ³ C+I ² C+3-wire/4-wire SPI
Operating temperature	$-40^{\circ}\text{C} \sim +105^{\circ}\text{C}$	$-40^{\circ}\text{C} \sim +85^{\circ}\text{C}$
Packaging	LGA (3.0x3.5x1.1 mm, 14 pins)	
Application	<ul style="list-style-type: none"> Automotive entertainment, automotive T-box, intelligent driving, integrated navigation system, anti-theft system, vibration monitoring and compensation 	<ul style="list-style-type: none"> Automotive safety systems
Mass production	<ul style="list-style-type: none"> Production-ready. Small batch production has started. 	/

Source: ResearchInChina

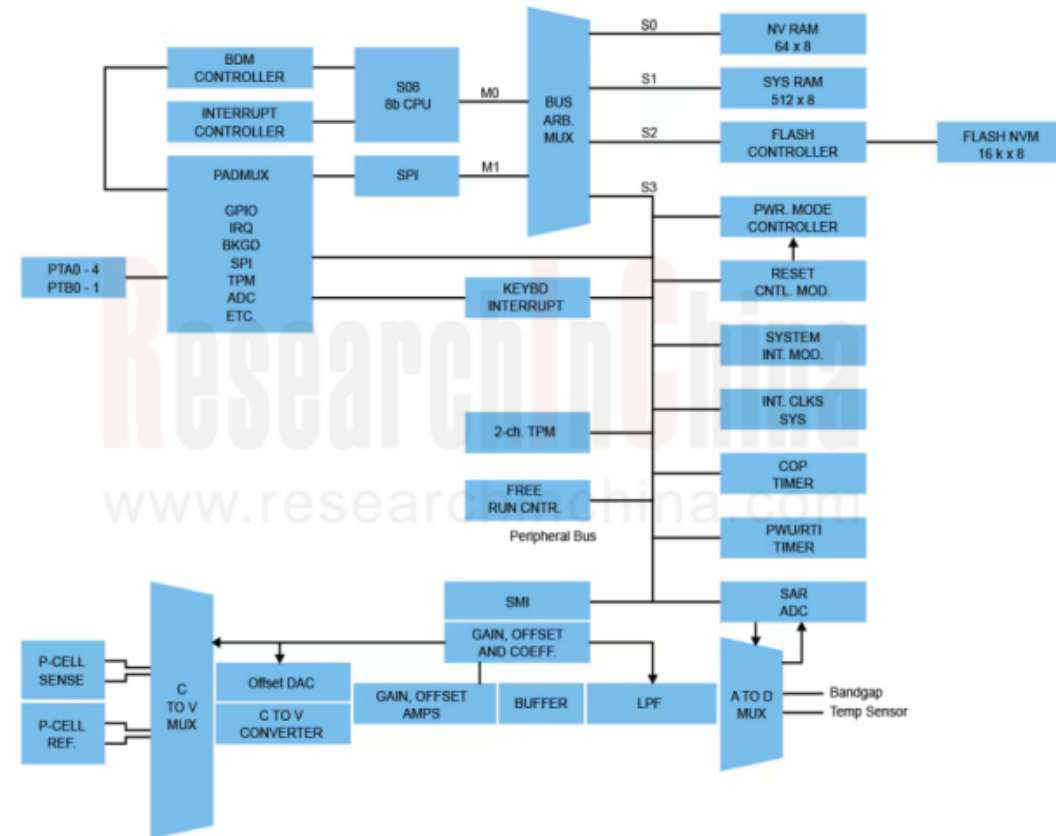
MEMS pressure sensors: MEMS pressure sensors will be used more widely in thermal runaway monitoring.

MEMS pressure sensors are largely seen in the power domain, chassis domain and cockpit domain of vehicles. In traditional ICE vehicles, MEMS pressure sensors find broad application in pressure detection of gearboxes and engines. In the field of new energy vehicles, the rapid development of electric vehicles may mean that the demand for pressure sensors in the power systems of traditional ICE vehicles will slow down. Meanwhile, some new application scenarios for MEMS pressure sensors will also appear. **For example, there are seat pressure sensors and heat pump air conditioning pressure and temperature composite sensors in the cockpit domain, and battery pack pressure sensors in the power domain. MEMS pressure sensors are expected to be used much more widely in thermal runaway monitoring in BMS.**

At present, the power batteries for new energy vehicles are led by lithium batteries. Overcharge, over-discharge, overheating, short circuit, high temperature, extrusion, collision, water intrusion and so on may cause thermal runaway of battery packs. In the case of thermal runaway, multiple chemical reactions will occur inside battery packs, generating heat and gas and increasing internal pressure of the batteries. At this time, the pressure change in the battery pack can be detected by pressure sensors.

NXP NBP8 and NBP9 is a fully integrated battery pressure monitor sensor family. This solution has a built-in MCU and battery pressure monitor sensors (BPMS), and integrates an 8-bit central processing unit (CPU) and firmware provided by NXP. NBP8xx can detect pressure and wake up the main MCU when a change in pressure is detected. The pressure sensors located in the battery monitoring unit communicate with the main MCU which then notifies the driver to escape from the vehicle quickly before thermal runaway occurs.

Block Diagram of NXP Battery Pressure Monitor Sensor NBP8-9x



Source: NXP

MEMS microphones: Intelligent driving perception will boost automotive MEMS silicon microphones.

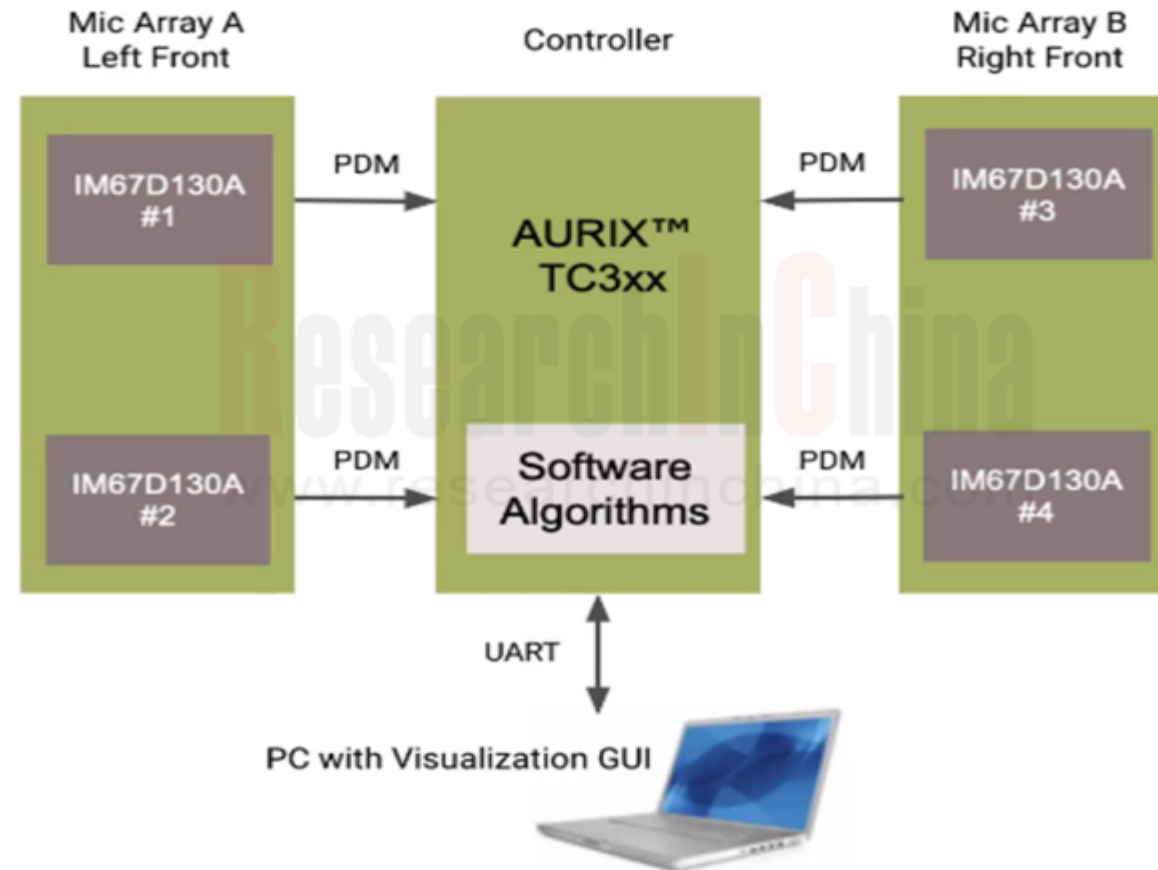
Automotive MEMS microphones can be used for in-vehicle and out-of-vehicle sound pickup. In-vehicle sound pickup applications mainly include hands-free calls, voice interaction, and active noise reduction. Out-of-vehicle sound pickup applications contain environmental perception and external voice pickup for road condition detection and (ambulance/police car) sirens detection.

ADAS generally collects data based on the position of cameras, radars or LiDAR and can only detect and recognize objects within its field of view. L3/L4 autonomous driving systems, there will be higher requirements for the detection of approaching emergency vehicles. L3/L4 autonomous driving requires vehicles to detect and respond to dynamic driving environments, such as ambulances, police cars and other emergency service vehicles. If the line of sight is blocked, vision-based perception is obviously unable to detect the approach of emergency vehicles in time.

Automotive MEMS microphones can provide vehicles with hearing capabilities, and perceive the approach of emergency vehicles in advance before visual sensors. Microphones with extremely high sensitivity can detect surrounding sounds without being heard by human ears, and warn of approaching objects in advance, leaving drivers or autonomous driving systems more time to respond, and improving the safety of the systems.

Infineon and Reality AI have jointly created an advanced sensing solution giving vehicles the sense of hearing. This solution adds XENSIV MEMS microphones to existing sensor systems. It enables cars to “see” around the corner and to warn about moving objects hidden in the blind spot or approaching emergency vehicles that are still too distant to see.

Block Diagram of Infineon’s Sensing Solution Based on Automotive MEMS Microphone IM67D130A



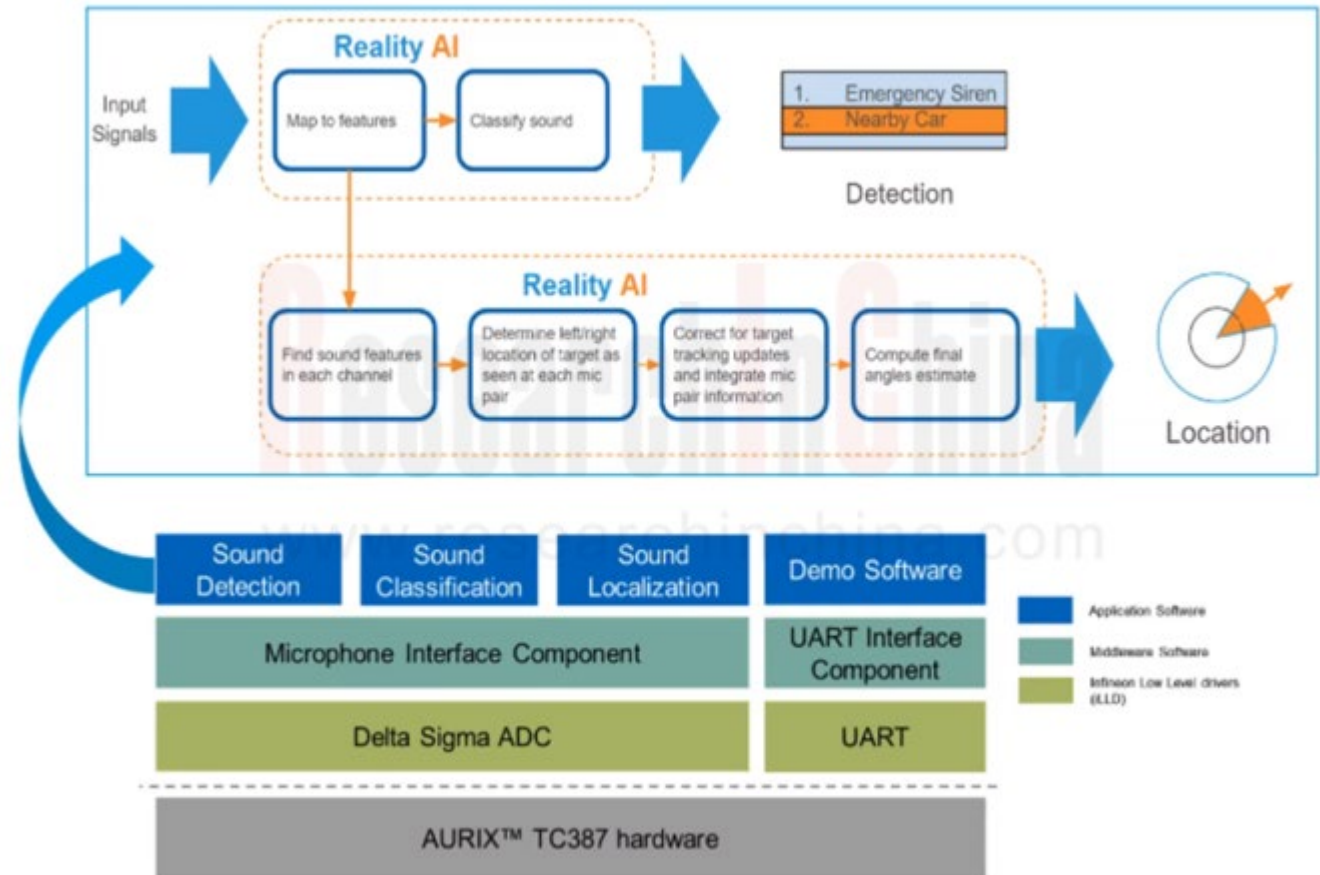
Source: Infineon

The new sensing solution is based on Infineon XENSIV MEMS microphones (IM67D130A) in combination with AURIX? microcontrollers (MCU) and Reality AI's Automotive See-With-Sound (SWS) system. Infineon IM67D130A has a low THD and an acoustic overload point (AOP) of 130dB SPL, which allows the automotive MEMS silicon microphone to capture distortion-free audio signals in noisy environments, thereby eliminating noise hidden in high background noise or wind noise and reliably recognizing alarm sounds in the system.

Using machine learning-based algorithms, the system is able to detect emergency vehicles, cars and other road participants – even if they cannot be seen by drivers or detected by the sensors incorporated in the vehicles' ADAS. Machine learning also ensures that the country-specific sirens of emergency vehicles are recognized in all parts of the world.

For processing the audio signal, the Reality AI software makes use of Infineon's AURIX TC3x family of MCUs which is widely used across multiple automotive applications. The scalable MCU family offers a range from one to six cores and up to 16 MB of Flash with functional safety up to ASIL-D according to the ISO26262 2018 standard and EVITA full cybersecurity.

Infineon Uses Reality AI's "SWS System" to Detect Emergency Vehicles



Source: Infineon

Table of Content (1)

1 Overview of Automotive MEMS Industry

1.1 Overview of MEMS Sensors

Classification of Automotive Sensors (by Information Collected)

Structure and Features of MEMS

Working Principle and Classification of MEMS

Application of MEMS Sensors in Automotive Electronics

Classification and Application of Automotive MEMS Sensors

MEMS Inertial Sensors: Classification and Application

MEMS Inertial Sensors: Accelerometer Architecture and Automotive Application

MEMS Inertial Sensors: Gyroscope Architecture and Automotive Application

MEMS Inertial Sensors: MEMS IMU Application Scenarios

MEMS Inertial Sensors: Key Technical Parameters

MEMS Inertial Sensors: Key Performance - Bias Instability

MEMS Pressure Sensors: Classification and Working Principle

MEMS Pressure Sensors: Automotive Application Classification (1)

MEMS Pressure Sensors: Automotive Application Classification (2)

MEMS Pressure Sensors: Automotive Application Classification (3)

MEMS Pressure Sensors: Application Comparison between Fuel Vehicles and Battery-electric Vehicles

MEMS Microphones: Structure and Working Principle

MEMS Microphones: Key Performance Indicators

MEMS Microphones: Automotive Application Scope

MEMS Microphones: Typical Automotive Scenarios - In-vehicle Sound Pickup

MEMS Microphones: Typical Automotive Scenarios - Out-of-vehicle Sound Pickup

MEMS Flow Sensors: Working Principle and Automotive Application

MEMS Temperature Sensors: Working Principle and Automotive Application

MEMS Temperature and Humidity Sensor: Automotive Applications

1.2 Automotive MEMS Sensor Standards

Automotive MEMS Sensor Certification Standard: AEC-Q103

Automotive MEMS Standardization Process in China

1.3 MEMS Market

Global MEMS Market Size, 2023-2029E (by Downstream Application)

Global MEMS Market Growth Rate, 2023-2029E (by Downstream Application)

Competitive Landscape of Global MEMS Sensor Industry

Competitive Landscape of China's MEMS Sensor Industry

1.4 Automotive MEMS Market

Barriers to Automotive MEMS Industry

Incremental Momentum for Automotive MEMS Market

Global Automotive MEMS Market Share (by Product Category)

MEMS Demand and Market Size in China's Passenger Car Market, 2023~2029E

Automotive MEMS Inertial Sensor Market: China's Automotive MEMS Inertial Sensor Market Landscape

Automotive MEMS Inertial Sensor Market: Automotive MEMS Accelerometer Price

Automotive MEMS Inertial Sensor Market: Automotive MEMS Gyroscope Price

Automotive MEMS Inertial Sensor Market: Automotive MEMS IMU Price

Automotive MEMS Inertial Sensor Market: Autonomous Driving Penetration Rate in China's Passenger Car Market, 2023~2028E

Automotive MEMS Inertial Sensor Market: China's Passenger Car MEMS Inertial Sensor Market Size, 2023~2028E (1)

Automotive MEMS Inertial Sensor Market: China's Passenger Car MEMS Inertial Sensor Market Size, 2023~2028E (2)

Automotive MEMS Pressure Sensor Market: China's Automotive MEMS Pressure Sensor Market Landscape

Table of Content (2)

Automotive MEMS Pressure Sensor Market: Growth Trend in the Automotive Field

Automotive MEMS Pressure Sensor Market: Long-term Trend of MEMS Pressure Sensors in Power Systems

Automotive MEMS Pressure Sensor Market: Automotive MEMS Pressure Sensor Price

Automotive MEMS Pressure Sensor Market: China's Passenger Car MEMS Pressure Sensor Market Size, 2023~2028E

Automotive MEMS Microphone Market: China's Automotive MEMS Microphone Market Landscape

Automotive MEMS Microphone Market: Automotive MEMS Silicon Microphone Price

Automotive MEMS Microphone Market: China's Passenger Car MEMS Microphone Market, 2023~2028E

1.5 MEMS Sensor Industry Chain

MEMS Sensor Industry Chain

Market Landscape of MEMS Sensor Industry Chain

Status Quo of China's MEMS Industry (1)

Status Quo of China's MEMS Industry (2)

MEMS Manufacturing: General Manufacturing Process of MEMS

MEMS Manufacturing: Three Processing Types of MEMS Substrates

MEMS Manufacturing Model: IDM and Fabless

Three Types of MEMS OEMs

Summary of MEMS OEMs and Production Lines in China (1)

Summary of MEMS OEMs and Production Lines in China (2)

Summary of MEMS OEMs and Production Lines in China (3)

MEMS Packaging: Technology Classification

2 Application Scenarios of Automotive MEMS Sensors - Autonomous Driving/ADAS

2.1 Application of MEMS Sensors in Intelligent Driving

Application of MEMS Sensors in Intelligent Driving Systems

Three Positioning Solutions for ADAS/Autonomous Driving Systems

Features, Advantages and Disadvantages of MEMS IMUs in High-precision Positioning

MEMS IMUs Become Key Sensors in Intelligent Driving

Application of MEMS IMUs in Intelligent Driving Solutions

Application of MEMS IMUs in Intelligent Driving (1): INS

Application of MEMS IMU in Intelligent Driving (2):

Application of MEMS IMU in Intelligent Driving (3)

Application of MEMS IMU in Intelligent Driving (4)

Three Integration Methods of "GNSS+IMU" Navigation (1): Loose Coupling

Three Integration Methods of "GNSS+IMU" Navigation (2)

Three Integration Methods of "GNSS+IMU" Navigation (3)

Three Integration Methods of "GNSS+IMU" Navigation (4)

Advanced Requirements for IMUs in End-to-end Intelligent Driving Solutions

Application and Difference of MEMS IMUs in End-to-end Intelligent Driving Solutions

Innovative Application of MEMS in Intelligent Driving Systems: MEMS Fast-moving Image Sensors

2.2 Application Solutions of MEMS Sensors in Intelligent Driving Scenarios and Product Summary

Summary of MEMS Accelerometers for Intelligent Driving (1)

Summary of MEMS Accelerometers for Intelligent Driving (2)

Summary of MEMS Gyroscopes for Intelligent Driving

Summary of MEMS IMUs for Intelligent Driving (1)

Summary of MEMS IMUs for Intelligent Driving (2)

Table of Content (3)

- Summary of MEMS IMUs for Intelligent Driving (3)
- Summary of MEMS IMUs for Intelligent Driving (4)
- Summary of MEMS IMUs for Intelligent Driving (5)
- Summary of MEMS IMUs for Intelligent Driving (6)
- Summary of MEMS IMUs for Intelligent Driving (7)
- Summary of MEMS Microphones for Intelligent Driving
- Intelligent Driving MEMS IMUs (1)
- Intelligent Driving MEMS IMUs (2)
- Intelligent Driving MEMS IMUs (3)
- Intelligent Driving MEMS IMUs (4)
- Intelligent Driving MEMS IMUs (5)
- Intelligent Driving MEMS IMUs (6)
- Intelligent Driving MEMS IMUs (7)
- Intelligent Driving MEMS Gyroscopes
- MEMS Application Solutions for Intelligent Driving Scenarios (1)
- MEMS Application Solutions for Intelligent Driving Scenarios (2)
- MEMS Application Solutions for Intelligent Driving Scenarios (3)
- MEMS Application Solutions for Intelligent Driving Scenarios (4)
- MEMS Application Solutions for Intelligent Driving Scenarios (5)

3 Application Scenarios of Automotive MEMS Sensors - Cockpit Entertainment

- 3.1 Application of MEMS Sensors in Intelligent Cockpits
 - Sensor Types in Intelligent Cockpits
 - Typical Applications of MEMS Silicon Microphones in Intelligent Cockpits (1):
 - Voice interaction & eCall
 - Typical Applications of MEMS Silicon Microphones in Intelligent Cockpits (2):
 - Automotive Noise Control
 - RNC System Market

- Typical Applications of MEMS Inertial Sensors in Intelligent Cockpits: Road Noise Cancellation (RNC)
- Typical Applications of MEMS Ultrasonic Sensors in Intelligent Cockpits: Rear Occupant Alert (ROA)

3.2 Application Solutions of MEMS Sensors in Intelligent Cockpit Scenarios and Product Summary

- Summary of MEMS Accelerometers for Intelligent Cockpits (1)
- Summary of MEMS Accelerometers for Intelligent Cockpits (2)
- Summary of MEMS Gyroscopes for Intelligent Cockpits
- Summary of MEMS IMUs for Intelligent Cockpits (1)
- Summary of MEMS IMUs for Intelligent Cockpits (2)
- Summary of MEMS Microphones for Intelligent Cockpits (1)
- Summary of MEMS Microphones for Intelligent Cockpits (2)
- Summary of MEMS Microphones for Intelligent Cockpits (3)
- MEMS Accelerometers for Intelligent Cockpits (1)
- MEMS Accelerometers for Intelligent Cockpits (2)
- MEMS Silicon Microphones for Intelligent Cockpits (1)
- MEMS Silicon Microphones for Intelligent Cockpits (2)
- MEMS Application Solutions for Intelligent Cockpit Scenarios (1)
- MEMS Application Solutions for Intelligent Cockpit Scenarios (2)
- MEMS Application Solutions for Intelligent Cockpit Scenarios (3)

4 Application Scenarios of Automotive MEMS Sensors - Body Electronics

- 4.1 Application of MEMS Sensors in Body Electronics
 - Main Sensors for Thermal Management Systems of New Energy Vehicles
 - Distribution of Pressure Sensors and Temperature Sensors in Thermal Management Systems of New Energy Vehicles

Table of Content (4)

Technical Route of Pressure/Temperature and Pressure Integrated Sensors in Traditional Refrigerant Systems

Sensor Solutions for Future Thermal Management Systems

Typical Applications of MEMS Sensors in Body Electronics (1)

Typical Applications of MEMS Sensors in Body Electronics (2)

Typical Applications of MEMS Sensors in Body Electronics (3)

Typical Applications of MEMS Sensors in Body Electronics (4)

4.2 Application Solutions of MEMS Sensors in Body Electronics and Product Summary

Summary of MEMS Accelerometers for Body Electronics (1)

Summary of MEMS Accelerometers for Body Electronics (2)

Summary of MEMS Gyroscopes for body electronics

Summary of MEMS IMUs for Body Electronics

Summary of MEMS Pressure Sensors for Body Electronics

MEMS Pressure Sensors for Body Electronics (1)

MEMS Pressure Sensors for Body Electronics (2)

MEMS Pressure Sensors for Body Electronics (3)

MEMS Application Solutions for Body Electronics (1)

MEMS Application Solutions for Body Electronics (2)

MEMS Application Solutions for Body Electronics (3)

MEMS Application Solutions for Body Electronics (4)

5 Application Scenarios of Automotive MEMS Sensors - Powertrain

5.1 Application of MEMS Sensors in Powertrains

Application MEMS Sensors in Automotive Engines

Application of MEMS Pressure Sensors in Power Domain

Typical Applications of MEMS Pressure Sensors in Powertrains (1): Engine Management Systems of Traditional Fuel Vehicles

Typical Applications of MEMS Pressure Sensors in Powertrains (2): Battery Pack Pressure Sensors for New Energy Vehicles

Typical Applications of MEMS IMUs in Powertrains

Main Sensors of New Energy Hydrogen Fuel Vehicles

5.2 Application Solutions of MEMS Sensors in Powertrains and Product Summary

Summary of MEMS Pressure Sensors for Powertrains (1)

Summary of MEMS Pressure Sensors for Powertrains (2)

Summary of MEMS Pressure Sensors for Powertrains (3)

Summary of MEMS Pressure Sensors for Powertrains (4)

Summary of MEMS Pressure Sensors for Powertrains (5)

Powertrain MEMS Pressure Sensors (1)

Powertrain MEMS Pressure Sensors (2)

MEMS Application Solutions for Powertrains (1)

MEMS Application Solutions for Powertrains (2)

MEMS Application Solutions for Powertrains (3)

MEMS Application Solutions for Powertrains (4)

6 Application Scenarios of Automotive MEMS Sensors - Chassis

6.1 Application of MEMS Sensors in Chassis

Sensors in Automotive Chassis Control Systems

Application of MEMS Pressure Sensors in Chassis Domain

Typical Applications of MEMS Sensors in Chassis (1): Suspension Systems

Typical Applications of MEMS Sensors in Chassis (2)

Typical Applications of MEMS Sensors in Chassis (3)

Typical Applications of MEMS Sensors in Chassis (4)

Development Trends of TMPS

Requirements of Autonomous Driving Systems for Intelligent Tire Technology

Requirements of Electrification for Intelligent Tire Technology

Table of Content (5)

6.2 Application Solutions of MEMS Sensors in Chassis and Product Summary

- Summary of MEMS Accelerometers for Chassis (1)
- Summary of MEMS Accelerometers for Chassis (2)
- Summary of MEMS Gyroscopes for Chassis
- Summary of MEMS IMUs for Chassis (1)
- Summary of MEMS IMUs for Chassis (2)
- Summary of MEMS Pressure Sensors for Chassis (1)
- Summary of MEMS Pressure Sensors for Chassis (2)
- Summary of MEMS Pressure Sensors for Chassis (3)
- Summary of MEMS Gyroscopes for Chassis (1)
- Summary of MEMS Gyroscopes for Chassis (2)
- MEMS Application Solutions for Chassis (1)
- MEMS Application Solutions for Chassis (2)
- MEMS Application Solutions for Chassis (3)

7 Foreign Automotive MEMS Sensor Suppliers

7.1 Bosch

- Automotive MEMS Sensor Application Scenarios and Product Selection
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Automotive MEMS Sensors (1)
- Automotive MEMS Sensors (2)
- Automotive MEMS Sensors (3)
- Automotive MEMS Sensors (4)
- Automotive MEMS IMU Application Solutions
- Automotive MEMS Acceleration Sensor Application Solutions (1)
- Automotive MEMS Acceleration Sensor Application Solutions (2)

7.2 STMicroelectronics

- Automotive MEMS Sensor Application Scenarios and Product Selection
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Automotive MEMS Sensors (1)
- Automotive MEMS Sensors (2)
- Automotive MEMS IMU Application Solutions
- Automotive MEMS Acceleration Sensor Application Solutions

7.3 ADI

- MEMS Sensor Layout
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Automotive MEMS Sensors
- Automotive MEMS Sensor Application Solutions (1)
- Automotive MEMS Sensor Application Solutions (2)

7.4 Infineon

- MEMS Sensor Layout
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Overview of Automotive MEMS Pressure Sensors
- Automotive MEMS Pressure Sensors (1)
- Automotive MEMS Pressure Sensors (2)
- Automotive MEMS Pressure Sensor Application Solutions
- Automotive MEMS Microphone Application Scenarios
- Automotive MEMS Silicon Microphones
- Automotive MEMS Silicon Microphone Application Solutions
- Automotive MEMS Silicon Microphone Application Solutions

Table of Content (6)

7.5 NXP

- Automotive MEMS Sensor Layout
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Automotive MEMS Pressure Sensors
- Automotive MEMS Pressure Sensor Application Solutions (1)
- Automotive MEMS Pressure Sensor Application Solutions (2)
- Automotive MEMS Pressure Sensor Application Solutions (3)
- Automotive MEMS Motion Sensor Application Solutions (4)

7.6 Melexis

- Automotive Electronic Product Line Layout
- Key Automotive MEMS Sensor Technologies (1)
- Key Automotive MEMS Sensor Technologies (2)
- Automotive MEMS Sensors: Summary of Products and Functional Features
- Automotive MEMS Pressure Sensors (1)
- Automotive MEMS Pressure Sensors (2)
- Automotive MEMS Pressure Sensors (3)
- Automotive MEMS Pressure Sensor Application Solutions

7.7 TDK

- Automotive Sensor Layout
- Key Automotive MEMS Sensor Processes
- Automotive MEMS IMU Application Scenarios
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Automotive MEMS Sensors
- Automotive MEMS Pressure Sensor Application Solutions
- Automotive MEMS Microphones

7.8 Murata

- Automotive Sensor Layout
- Automotive MEMS Sensor Application Scenarios and Product Selection
- Key Automotive MEMS Sensor Processes (1)
- Key Automotive MEMS Sensor Processes (2)
- Key Automotive MEMS Sensor Processes (3)
- Automotive MEMS Sensors: Summary of Products and Functional Features (1)
- Automotive MEMS Sensors: Summary of Products and Functional Features (2)
- Automotive MEMS Sensors (1)
- Automotive MEMS Sensors (2)
- Automotive MEMS Sensors (3)

7.9 Sensata

- Automotive Sensor Lineup
- Automotive MEMS Pressure Sensor Layout
- Sensor Application Layout in BEVs
- Sensor Application Layout in PHEVs
- Sensor Application Layout in Electric Commercial Vehicles
- Automotive MEMS Pressure Sensor Application Solutions (1)
- Automotive MEMS Pressure Sensor Application Solutions (2)
- Automotive MEMS Pressure Sensor Application Solutions (3)

7.10 Panasonic

- Automotive MEMS Sensors (1)
- Automotive MEMS Sensors (2)
- Automotive MEMS IMU Application Solutions (1)
- Automotive MEMS IMU Application Solutions (2)

Table of Content (7)

8 Chinese Automotive MEMS Sensor Suppliers

8.1 Anhui XDLK Microsystem

MEMS Sensor Layout

MEMS Sensor Application Scenarios

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors

8.2 NOVOSENSE

Automotive Sensor Solutions

Automotive MEMS Sensors: Summary of Products and Functional Features (1)

Automotive MEMS Sensors: Summary of Products and Functional Features (2)

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

Automotive MEMS Sensors (3)

Automotive MEMS Pressure Sensor Application Solutions (1)

Automotive MEMS Pressure Sensor Application Solutions (2)

8.3 Ampron

Sensor Layout

Automotive MEMS Sensor Classification and Application Scenarios

Key Automotive MEMS Sensor Processes

Automotive MEMS Sensor Customers

Automotive MEMS Sensors: Summary of Products and Functional Features (1)

Automotive MEMS Sensors: Summary of Products and Functional Features (2)

Automotive MEMS Pressure Sensors (1)

Automotive MEMS Pressure Sensors (2)

8.4 QST

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS IMUs (1)

Automotive MEMS IMUs (2)

8.5 MiraMEMS

Key Automotive MEMS Sensor Processes

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors

8.6 AAC Technologies

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

Automotive MEMS Sensors (3)

8.7 MEMSIC

Automotive Application Solutions

Key Automotive MEMS Sensor Processes (1)

Key Automotive MEMS Sensor Processes (2)

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors

Automotive MEMS Acceleration Sensor Application Solutions

8.8 MT Microsystems

Automotive Sensor Layout

Key Automotive MEMS Pressure Sensor Processes

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors

Automotive MEMS Sensor Application Solutions

8.9 MEMSensing

Key Automotive MEMS Pressure Sensor Processes

Automotive MEMS Sensors: Summary of Products and Functional Features (1)

Automotive MEMS Sensors: Summary of Products and Functional Features (2)

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

Table of Content (8)

8.10 Asensing Technology

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

8.11 Huaxin Semiconductor

Automotive MEMS Sensors: Summary of Products and Functional Features

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

Automotive MEMS Sensors (3)

8.12 Rsentech

MEMS Automotive Sensors (1)

MEMS Automotive Sensors (2)

8.13 Winsen

Automotive Sensor Layout

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

8.14 ASAIR

Smart Traffic Sensor Solutions

Automotive MEMS Sensors (1)

Automotive MEMS Sensors (2)

8.15 NationalChip

Automotive MEMS Sensors



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